

More Precision

wireSENSOR // Draw-wire mechanics for installation of rotary encoders



Draw-wire mechanics for individual encoder installation wireSENSOR

Measuring ranges up to 50,000 mm

Compact design with large measuring range

Easy, quick and flexible installation

High operational safety & long service life

Ideal for custom design and large quantities

Analog and digital outputs



Measuring principle

Draw-wire displacement sensors measure linear movements using a highly flexible steel wire. High quality components ensure a long service life and high operational reliability.

Micro-Epsilon offers numerous models based on different draw-wire mechanical principles to connect different rotary encoders. For special applications involving large quantities, we develop and manufacture customized OEM designs.

wireSENSOR models stand out due to their optimized ratio between measuring range and size, easy installation and handling. Their robust sensor design enables applications in harsh ambient conditions.

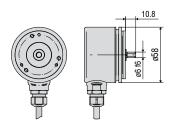


Robust draw-wire mechanics for encoder installation

The wireSENSOR mechanics are designed for mounting incremental or absolute encoders. This means that the interface, resolution and type of connection can be individually determined and adapted to the signal processing. High-quality precision components and a robust design ensure high operational safety and a long service life even under harsh industrial conditions.

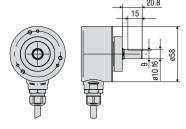
A complete measuring unit consists of the basic draw-wire mechanics and the adapter for the customer-specific encoder. The adapter contains all the necessary mounting accessories for mounting your encoder.

The following encoder types can be installed by default:



Synchro flange (standard) with WDS-EASxx adapter

- Housing size 58 mm
- Shaft diameter 6 mm
- Shaft length 10 mm



Clamping flange with WDS-EACxx adapter

- Housing size 58 mm
- Shaft diameter 10 mm
- Shaft length 20 mm

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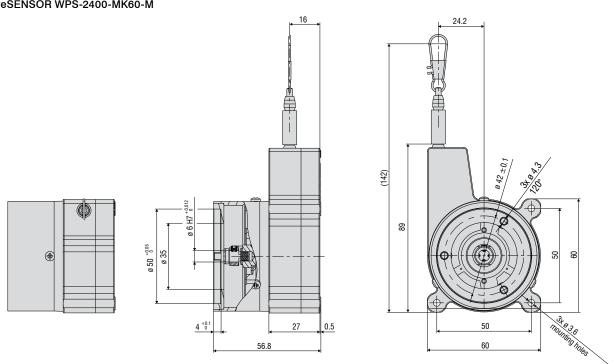
Draw-wire sensor mechanics with plastic housing

MK60-M

| Model | | WPS-2400-MK60-M |
|--|----------------------|---|
| Measuring range | static (20 Hz) | 2400 mm |
| Output type | | dependent on encoder |
| Resolution | static (20 Hz) | dependent on encoder |
| Linearity | $\leq \pm 0.1$ % FSO | ≤ ±2.4 mm |
| Mean distance per rotation | | 150.75 mm |
| Suitable rotary encoder | | Flange type ø 58 mm: synchro flange ø 6 mm shaft |
| Adapter flange for rotary encoder ø 58 | Synchro flange | included in delivery |
| Wire extension force (max) | | 8 N |
| Wire retraction force (min) | | 1 N |
| Wire acceleration (max.) | | 5 g |
| Material | Housing | Plastics |
| Ivialcital | Measuring wire | polyamide-coated stainless steel (ø 0.45 mm) |
| Wire mounting | | Wire clip |
| Installation | | Mounting holes |
| Temperature range | Storage | -40 +85 °C |
| iemperature range | Operation | -40 +85 °C |
| Shock (DIN EN 60068-2-29) | | $50\ g\ /\ 5$ ms in 3 axes, 2 directions and 1000 shocks each |
| Vibration (DIN EN 60068-2-6) | | 20 g / 20 Hz 2 kHz in 3 axes and 10 cycles each |
| Protection class (DIN EN 60529) | | dependent on encoder |
| Weight | | 0.2 kg |

FSO = Full Scale Output
All data refer to the mechanics without encoder

wireSENSOR WPS-2400-MK60-M



Draw-wire sensor mechanics with plastic housing

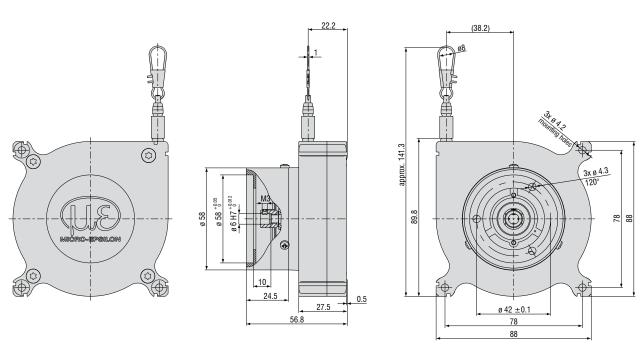
MK88-M

| Model | | WPS-2300-MK88-M | WPS-3500-MK88-M | WPS-5000-MK88-M | | |
|--|-----------------------|---|---|--------------------------------------|--|--|
| Measuring range | | 2300 mm 3500 mm 5000 mm | | | | |
| Output type | | | dependent on encoder | | | |
| Resolution | static (20 Hz) | | dependent on encoder | | | |
| | ≤ ±0.1 % FSO | ≤ ±2.3 mm | - | - | | |
| inearity | $\leq \pm 0.3 \%$ FSO | - | ≤ ±10.5 mm | - | | |
| | ≤ ±0.4 % FSO | - | - | ≤ ±20 mm | | |
| Mean distance per rotation | | 237.8 mm | 238.1 mm | 238.7 mm | | |
| Suitable rotary encoder | | Flange | type ø 58 mm: synchro flange ø 6 mm | n shaft | | |
| Adapter flange for otary encoder ø 58 | Synchro flange | included in delivery | | | | |
| Vire extension force (max) | | approx. 9 N | | | | |
| Vire retraction force (min) | | approx. 4 N | | | | |
| Vire acceleration (max.) | | approx. 7 g | | | | |
| ∕laterial | Housing | Plastics | | | | |
| idleridi | Measuring wire | poly | vamide-coated stainless steel (ø 0.45 n | e-coated stainless steel (ø 0.45 mm) | | |
| Vire mounting | | Wire clip | | | | |
| nstallation | | Mounting h | noles or mounting grooves on the sens | or housing | | |
| amparatura ranga | Storage | -20 +80 °C | | | | |
| emperature range | Operation | -20 +80 °C (on request -40 +85 °C) | | | | |
| Shock (DIN EN 60068-2-29) | | 50 g / 10 ms in 3 axes, 2 directions and 1000 shocks each | | | | |
| /ibration (DIN EN 60068-2-6) | | 20 g / 20 Hz \dots 2 kHz in 3 axes and 10 cycles each | | | | |
| Protection class (DIN EN 60529) | | dependent on encoder | | | | |
| Veight | | 0.5 kg | | | | |

FSO = Full Scale Output

All data refer to the mechanics without encoder

wireSENSOR WPS-MK88-M



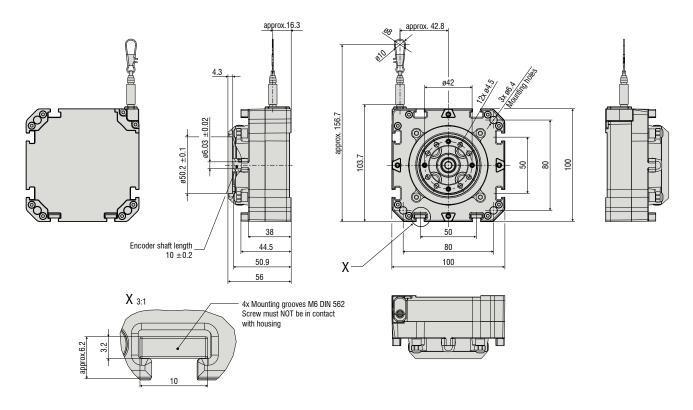
Draw-wire sensor mechanics with plastic housing **WPS-K100-M**

| Model | | WPS-1500-K100-M | WPS-2500-K100-M | WPS-3500-K100-M | WPS-5000-K100-M | WPS-8000-K100-M | | |
|--|----------------|--|---|--------------------------|------------------------|--|--|--|
| Measuring range | | 1500 mm | 2500 mm | 3500 mm | 5000 mm | 8000 mm | | |
| Output type | | dependent on encoder | | | | | | |
| Resolution | Resolution | | dependent on encoder | | | | | |
| Line and the | ≤ ±0.10 % FSO | ≤ ±1.5 mm | ≤ ±2.5 mm | ≤ ±3.5 mm | ≤ ±5 mm | - | | |
| Linearity | ≤ ±0.25 % FSO | - | - | - | - | ≤ ±20 mm | | |
| Mean distance per rotation | | | 263.6 mm | | 263.1 mm | 263.75 mm | | |
| Suitable rotary encoder | | | Flange type ø | 58 mm: synchro flange | ø 6 mm shaft | | | |
| Adapter flange for rotary encoder ø 58 | Synchro flange | included in delivery | | | | | | |
| Wire extension force (max) | | approx. 10 N | | | | | | |
| Wire retraction force (min) | | approx. 2 N | | | | | | |
| Wire acceleration (max.) | | approx. 5 g | | | | | | |
| | Housing | Glass-fiber reinforced plastic | | | | | | |
| Material | Measuring wire | | Polyamide-coated stainless steel (ø 0.61 mm) | | | Polyamide-coated stainless steel (ø 0.45 mm) | | |
| Wire mounting | | | Wire clip | | | | | |
| Installation | | Thr | ough-bores ø 6.4 mm a | and mounting nuts (for I | M6) on the sensor hous | sing | | |
| Temperature range | Storage | -40 +85 °C | | | | | | |
| lemperature range | Operation | | | -40 +85 °C | | | | |
| Shock (DIN EN 60068-2-29) | | | 50 g / 8 ms in 3 a | exes, 2 directions and 1 | 000 shocks each | | | |
| Vibration (DIN EN 60068-2-6) | | 5 g / 10 \dots 150 Hz in 3 axes and 20 cycles each | | | | | | |
| Protection class (DIN EN 60529) | | dependent on encoder | | | | | | |
| Weight | | | | approx. 500 g | | | | |
| FSO - Full Scale Output | | | | | | | | |

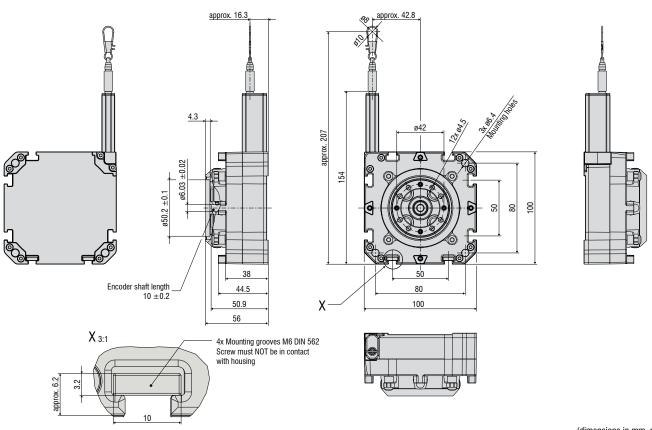
FSO = Full Scale Output

All data refer to the mechanics without encoder

WPS-1500-K100-M / WPS-2500-K100-M



WPS-3500-K100-M / WPS-5000-K100-M / WPS-8000-K100-M



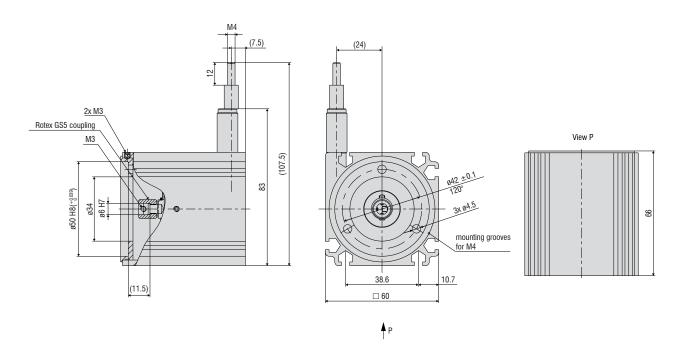
P60-M

| Model | | WDS-2000-P60-M |
|---------------------------------|----------------|---|
| Measuring range | static (20 Hz) | 2000 mm |
| Output type | | dependent on encoder |
| Resolution | static (20 Hz) | dependent on encoder |
| Linearity | ≤ ±0.02 % FSO | ≤ ±0.4 mm |
| Mean distance per rotation | | 150 mm |
| Suitable rotary encoder | | Flange type ø 58 mm: synchro flange ø 6 mm shaft |
| Wire extension force (max) | | 7 N |
| Wire retraction force (min) | | 3.5 N |
| Wire acceleration (max.) | | 10 g |
| Material | Housing | Aluminum |
| Material | Measuring wire | polyamide-coated stainless steel (ø 0.45 mm) |
| Wire mounting | | M4 threaded bolts |
| Installation | | Mounting grooves on the sensor housing |
| Temperature range | Storage | -40 +80 °C |
| Temperature range | Operation | -20 +80 °C |
| Shock (DIN EN 60068-2-29) | | 50 g / 10 ms in 3 axes, 2 directions and 1000 shocks each |
| Vibration (DIN EN 60068-2-6) | | 20 g / 20 Hz \dots 2 kHz in 3 axes and 10 cycles each |
| Protection class (DIN EN 60529) | | dependent on encoder |
| Weight | | 1 kg |

FSO = Full Scale Output

All data refer to the mechanics without encoder

wireSENSOR WDS-2000-P60-M



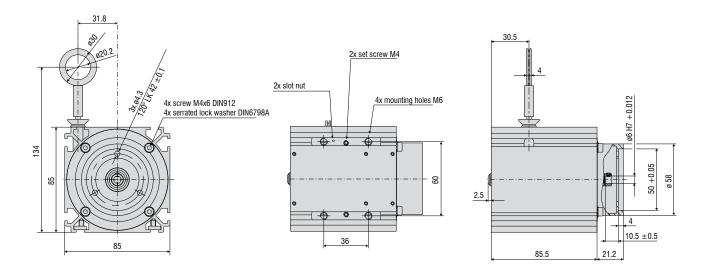
P85-M

| Model | | WDS-2500-P85-M |
|---------------------------------|------------------------|---|
| Measuring range | static (20 Hz) | 2500 mm |
| Output type | | dependent on encoder |
| Resolution | static (20 Hz) | dependent on encoder |
| Linearity | $\leq \pm 0.02 \%$ FSO | ≤ ±0.5 mm |
| Mean distance per rotation | | 199.8 mm |
| Suitable rotary encoder | | Flange type ø 58 mm: synchro flange ø 6 mm shaft, clamping flange ø 10 mm shaft |
| Adapter flange for | Synchro flange | included in delivery |
| rotary encoder ø 58 mm | Clamping flange | WDS-EAC115 |
| Wire extension force (max) | | 16 N |
| Wire retraction force (min) | | 6 N |
| Wire acceleration (max.) | | 5 g |
| Material | Housing | Aluminum |
| ividieridi | Measuring wire | polyamide-coated stainless steel (ø 1.2 mm) |
| Wire mounting | | Eyelet (ø 30 mm) |
| Installation | | Mounting grooves on the sensor housing |
| Temperature range | Storage | -40 +80 °C |
| lemperature range | Operation | -20 +80 °C |
| Shock (DIN EN 60068-2-29) | | $50\ g$ / $10\ ms$ in 3 axes, 2 directions and 1000 shocks each |
| Vibration (DIN EN 60068-2-6) | | 20 g / 20 Hz \dots 2 kHz in 3 axes and 10 cycles each |
| Protection class (DIN EN 60529) | | dependent on encoder |
| Weight | | 1 kg |

FSO = Full Scale Output

All data refer to the mechanics without encoder

wireSENSOR WDS-2500-P85-M



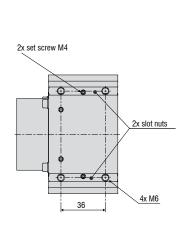
P96-M

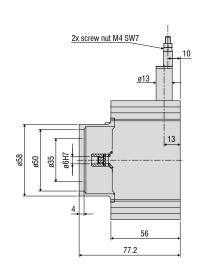
| Model | | WDS-3000-P96-M |
|---|-----------------|---|
| Measuring range | static (20 Hz) | 3000 mm |
| Output type | | dependent on encoder |
| Resolution | static (20 Hz) | dependent on encoder |
| Linearity | ≤ ±0.02 % FSO | ≤ ±0.6 mm |
| Mean distance per rotation | | 260.09 mm |
| Suitable rotary encoder | | Flange type ø 58 mm: synchro flange ø 6 mm shaft, clamping flange ø 10 mm shaft |
| Adapter flange for rotary encoder ø 58 mm | Synchro flange | included in delivery |
| | Clamping flange | WDS-EAC 96/200 |
| Wire extension force (max) | | 10 N |
| Wire retraction force (min) | | 5 N |
| Wire acceleration (max.) | | 7 g |
| Material | Housing | Aluminum |
| Waterial | Measuring wire | polyamide-coated stainless steel (ø 0.8 mm) |
| Wire mounting | | M4 threaded bolts |
| Installation | | Slot nuts |
| Temperature range | Storage | -40 +80 °C |
| remperature range | Operation | -20 +80 °C |
| Shock (DIN EN 60068-2-29) | | 50 g / 10 ms in 3 axes, 2 directions and 1000 shocks each |
| Vibration (DIN EN 60068-2-6) | | 20 g / 20 Hz \dots 2 kHz in 3 axes and 10 cycles each |
| Protection class (DIN EN 60529) | | dependent on encoder |
| Weight | | 1.1 kg |
| | | |

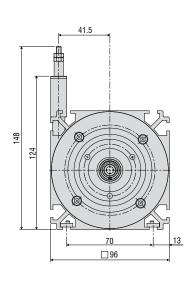
FSO = Full Scale Output

All data refer to the mechanics without encoder

wireSENSOR WDS-3000-P96-M







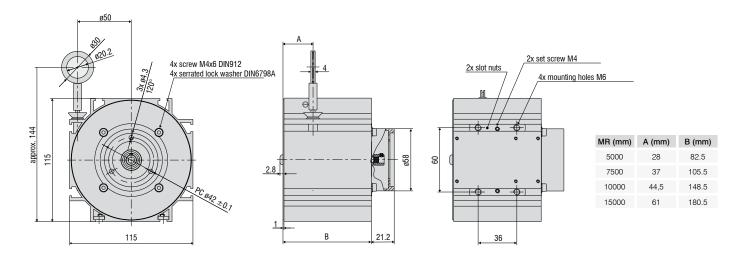
P115-M

| Model | | WDS-5000-P115-M | WDS-7500-P115-M | WDS-10000-P115-M | WDS-15000-P115-M | | |
|---------------------------------|------------------------|---|-----------------------------|-----------------------------|------------------|--|--|
| Measuring range | static (20 Hz) | 5000 mm | 7500 mm | 10000 mm | 15000 mm | | |
| Output type | | dependent on encoder | | | | | |
| Resolution | static (20 Hz) | | dependent | on encoder | | | |
| Linearity | ≤ ±0.01 % FSO | - | - | ≤ ±1 mm | ≤ ±1.5 mm | | |
| Lineality | $\leq \pm 0.02 \%$ FSO | ≤ ±1 mm | ≤ ±1.5 mm | - | - | | |
| Mean distance per rotation | | | 315.0 | 7 mm | | | |
| Suitable rotary encoder | | Flange type | ø 58 mm: synchro flange ø 6 | mm shaft, clamping flange ø | 10 mm shaft | | |
| Adapter flange for | Synchro flange | | included i | n delivery | | | |
| rotary encoder ø 58 mm | Clamping flange | | WDS-E | AC 115 | | | |
| Wire extension force (max) | | 16 N | 24 N | 21 N | 25 N | | |
| Wire retraction force (min) | | 4 N | 8 N | 8 N | 8 N | | |
| Wire acceleration (max.) | | 5 g | 6 g | 3 g | 3 g | | |
| Material | Housing | Aluminum | | | | | |
| Material | Measuring wire | | polyamide-coated stai | nless steel (ø 1.0 mm) | | | |
| Wire mounting | | | Eyelet (ø | 30 mm) | | | |
| Installation | | | Slot | nuts | | | |
| Tomporatura ranga | Storage | -40 +80 °C | | | | | |
| Temperature range | Operation | -20 +80 °C | | | | | |
| Shock (DIN EN 60068-2-29) | | 50 g / 10 ms in 3 axes, 2 directions and 1000 shocks each | | | | | |
| Vibration (DIN EN 60068-2-6) | | 20 g / 20 Hz 2 kHz in 3 axes and 10 cycles each | | | | | |
| Protection class (DIN EN 60529) | | dependent on encoder | | | | | |
| Weight | | 1.4 kg | 1.9 kg | 2.8 kg | 3.2 kg | | |
| | | | | | | | |

FSO = Full Scale Output

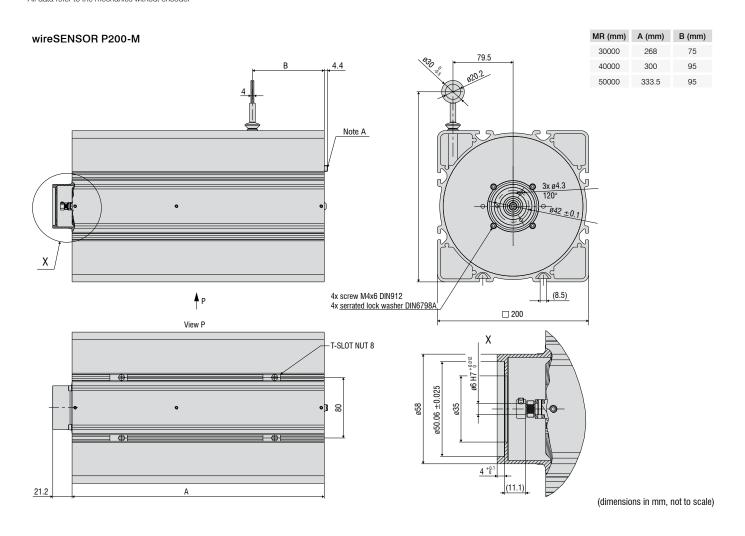
All data refer to the mechanics without encoder

wireSENSOR WDS-P115-M



| Model | | WDS-30000-P200-M | WDS-40000-P200-M | WDS-50000-P200-M | | |
|---------------------------------|-----------------|---|---------------------------------------|------------------------|--|--|
| Measuring range | static (20 Hz) | 30000 mm | 40000 mm | 50000 mm | | |
| Output type | | | dependent on encoder | | | |
| Resolution | static (20 Hz) | dependent on encoder | | | | |
| Linearity | ≤ ±0.01 % FSO | $\leq \pm 3 \text{ mm}$ $\leq \pm 4 \text{ mm}$ $\leq \pm 5 \text{ mm}$ | | | | |
| Mean distance per rotation | | | 500 mm | | | |
| Suitable rotary encoder | | Flange type ø 58 mm: | synchro flange ø 6 mm shaft, clamping | g flange ø 10 mm shaft | | |
| Adapter flange for | Synchro flange | | included in delivery | | | |
| rotary encoder ø 58 mm | Clamping flange | | WDS-EAC 96/200 | | | |
| Wire extension force (max) | | 22 N | 22 N | 24 N | | |
| Wire retraction force (min) | | 12 N 11 N 11 N | | | | |
| Wire acceleration (max.) | | 2 g | | | | |
| Material | Housing | Aluminum | | | | |
| Malerial | Measuring wire | polyamide-coated stainless steel (ø 0.8 mm) | | | | |
| Wire mounting | | Eyelet (ø 30 mm) | | | | |
| Installation | | | Slot nuts | | | |
| Tomporatura ranga | Storage | e -40 +80 °C | | | | |
| Temperature range | Operation | | -20 +80 °C | | | |
| Vibration (DIN EN 60068-2-6) | | 20 g / | 20 Hz 2 kHz in 3 axes and 10 cycles | s each | | |
| Protection class (DIN EN 60529) | | dependent on encoder | | | | |
| Weight | | 9.5 kg 10 kg 11 kg | | | | |
| F00 F #0 + 0 + + | | | | | | |

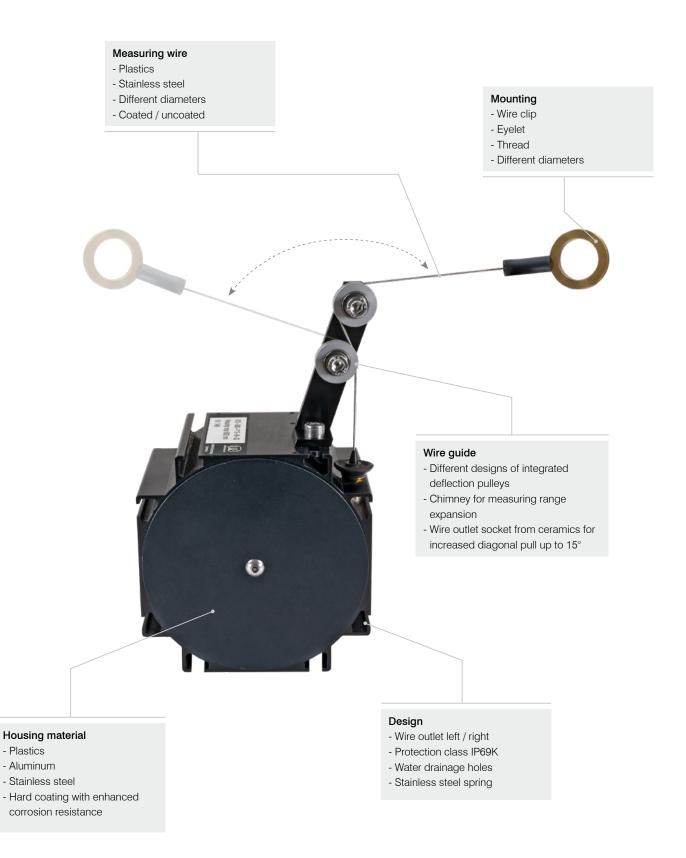
FSO = Full Scale Output
All data refer to the mechanics without encoder



Options wireSENSOR

Customized draw-wire mechanics

Micro-Epsilon also develops sensors for special requirements that are not met by standard models. Draw-wire mechanics from the standard range can be modified accordingly. Low-cost implementation can already be achieved with medium-sized quantities (depending on the type and number of changes).



OEM examples

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Z60 Sensor mechanics / stainless steel housings

Sensor mechanics entirely made from stainless steel for difficult ambient conditions (salt water)



MK88 Sensor mechanics to monitor telescopic booms

- Integrated deflection pulley made from plastic with secured "wire guidance"
- High spring force
- IP67 / -40 °C ... 80 °C
- Robust plastic housing



MK88-M Snap-protected sensors with plastic housing

Measuring wire can snap back from a distance up to 60 cm without damaging the measuring wire or the sensor.



P115 Sensor mechanics with aluminum housing and drainage holes

- Drainage holes to drain condensed water
- Suitable for outdoor applications
- Measuring ranges up to 15,000 mm

Wire-sensor mechanics for PCB integration

wireSENSOR



Integration of PCBs

These draw-wire mechanics can be configured to directly connect with a PCB. With this variant, the PCB is directly connected to the sensor mechanics. Depending on the needs, the installation can be performed at the factory or by the customer.

MK60 and M88 mechanics for PCB integration are available from stock. With a certain number of pieces, other series may also be used for PCB integration.

Compared with conventional encoders, PCB solutions offer a great cost advantage. As the functionality of PCBs usually is sufficient, this price advantage can be optimally used with draw-wire sensors from Micro-Epsilon.



Magnets are available in different designs.

Accessories

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Adapter flanges

Synchro flange Standard WDS-EAS115



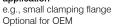
Clamping flange Option WDS-EAC115



Synchro flange for MK series Standard

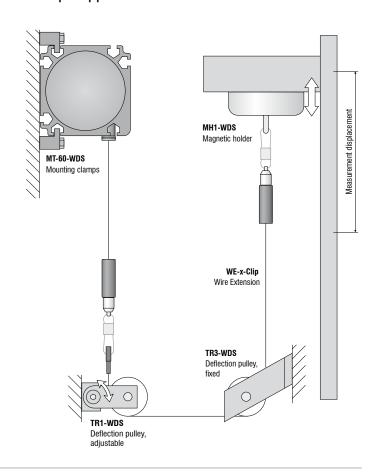


Different adaptions for OEM application





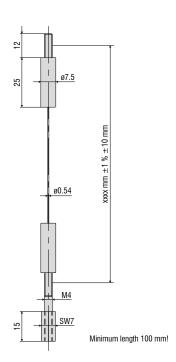
Example application with accessories



Wire extensions

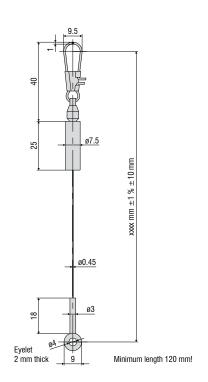
WF-xxxx-M4

Wire extension with M4 wire connection, x=wire length



WE-xxxx-Clip

Wire extension with eyelet, x = wire length



Installation options

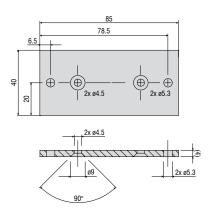
WDS-MP60 Mounting plate for P60 models

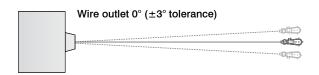


Installation instructions:

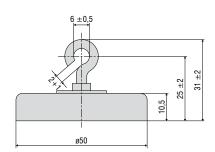
Wire attachment: during installation, do not allow at any time the measuring wire to freely return.

Angle of wire outlet: Make sure during installation that the wire outlet is straight (tolerance of $\pm 3^{\circ}$). Exceeding this tolerance leads to increased wear of the wire material and on the wire outlet.



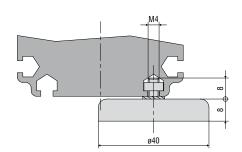


MH1-WDS
Magnetic holder for wire attachment

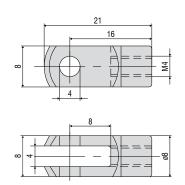


MH2-WDS

Magnetic holder for sensor mounting

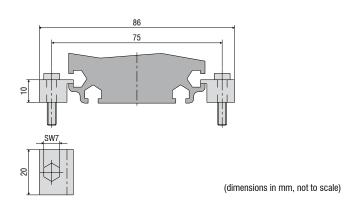


GK1-WDSFork head for M4



MT-60-WDS

Mounting clamps for WDS-P60



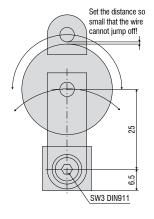
Accessories

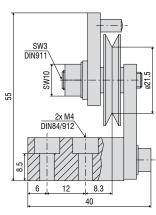
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Wire deflection pulleys for external installation

TR1-WDS Wire deflection pulley, adjustable, for sensors with a wire diameter \leq 0.45 mm



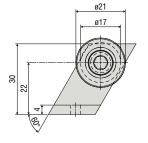


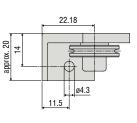


TR3-WDS

Wire deflection pulley, fixed, for sensors with a wire diameter $\leq 0.45 \ \text{mm}$



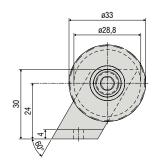


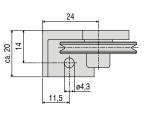


TR4-WDS

Wire deflection pulley, fixed, for sensors with a wire diameter of 0.8 mm to 1 mm



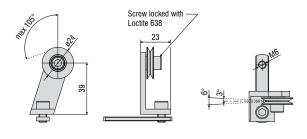




Wire deflection pulley for direct installation on the sensor housing

TR5-WDS Integrated wire deflection pulley for P115 sensors with a wire diameter of 0.45 mm

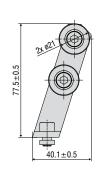


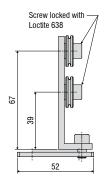


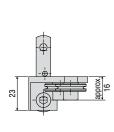
TR5-WDS(03)

Integrated double deflection pulley for P115 sensors with a wire diameter of 0.45 mm



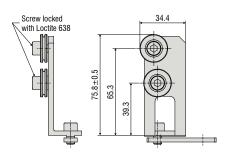


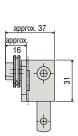




TR5-WDS(04) Integrated double deflection pulley, 90° angled, for P115 sensors with a wire diameter of 0.45 mm

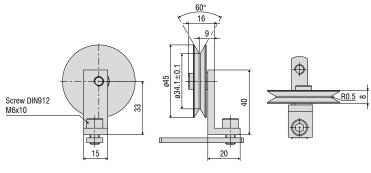






TR6-WDS(01)
Integrated wire deflection pulley for the P115 sensors with a wire diameter of 1 mm





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