Laser scanner
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1. **Safety**

The handling of the sensor assumes knowledge of the instruction manual.

1.1 **Symbols**

The following symbols are used in this instruction manual:

- **CAUTION** Indicates a hazardous situation which, if not avoided, may result in minor or moderate injury.
- **NOTICE** Indicates a situation which, if not avoided, may lead to property damage.
- Indicates a user action.
- Indicates a user tip.
- **Measure** Indicates a hardware or a button/menu in the software

1.2 **Warnings**

- **CAUTION** The power supply and the display-/output device must be connected in accordance with the safety regulations for electrical equipment
  - > Danger of injury
  - > Damage to or destruction of the sensor

- **NOTICE** Avoid shock and vibration to the sensor.
  - > Damage to or destruction of the sensor

The power supply may not exceed the specified limits.
> Damage to or destruction of the sensor

Avoid continuous exposure to dust and spray on the sensor by appropriate methods such as blowing or using a protective housing.
> Damage to or destruction of the sensor

Do not touch the protective windows of the optics with the fingers. Wipe off any fingerprints immediately with pure alcohol and a clean cotton cloth with no streaks.
Protect the cable against damage.
> Failure of the measuring device

Do not plug or unplug devices during the operation.

1.3 **Notes on CE Identification**

The following applies to the scanCONTROL 29xx/BL sensor:
- EU directive 2014/30/EU
- EU directive 2011/65/EU, “RoHS“ category 9

Products which carry the CE mark satisfy the requirements of the quoted EU directives and the European standards (EN) listed therein. The EC declaration of conformity is kept available according to EC regulation, article 10 by the authorities responsible at

MICRO-EPSILON MESSTECHNIK
GmbH & Co. KG
Königbacher Straße 15
94496 Ortenburg / Germany

The sensor is designed for use in industry and satisfies the requirements.

1.4 **Proper Use**
- The scanCONTROL 29xx/BL sensor is designed for use in industrial and laboratory areas.
- It is used for
  - Profile measurement
  - Length measurement
  - Quality monitoring and inspection of dimensions
- The sensor may only be operated within the limits specified in the technical data, see Chap. 3.2.
- The sensor should only be used in such a way that in case of malfunction or failure personnel or machinery are not endangered.
- Additional precautions for safety and damage prevention must be taken for safety-related applications.
1.5 Proper Environment

- Protection class for sensors: IP 65 (applies only when connected output connectors respectively protective caps)
- Operating temperature: 0 ... +45 °C (+32 ... +113 °F) (with free air circulation)
- Ambient pressure: Atmospheric pressure
- Storage temperature: -20 ... +70 °C (-4 ... +158 °F)
- Humidity: 5 - 95 % (non condensing)

The protection class does not apply for the optical sections during operation as their soiling / contamination results in adversely affecting or failure of the function.

Only use shielded cables or original cables from the range of accessories for the connection to a power supply and for the outputs.

Note also the assembly and installation instructions, see Chap. 5.

The IP 65 protection class is a specification which is limited to the protection with respect to dust and water. Oil, steam and emulsion penetration are not included in this protection class and must be tested separately.
2. Laser Safety

The scanCONTROL 29xx/BL sensors operate with a semiconductor laser having a wavelength of 405 nm (visible/blue). The laser operation is indicated visually by the LED on the sensor.

When operating the scanCONTROL 29xx/BL sensors, the relevant regulations according to EN 60825-1 (IEC 60825, Part 1 of 05/2008) and the applicable accident prevention regulations must be followed.

The housings of the scanCONTROL 29xx/BL optical sensors must only be opened by authorized persons, see Chap. 8. For repair and service, the sensors should always be returned to the manufacturer.

scanCONTROL 29xx/BL sensors with a maximum laser power up to 8 mW, see Chap. 3.2, are classified in Laser Class 2M (IIM).

Accordingly, the following applies:

With laser equipment of the Class 2M, the eye is not put in danger during random, short-term exposure to the laser radiation, i.e. exposure duration up to 0.25 s.

A direct glimpse into the beam can be dangerous if the eye-closure reflex is deliberately suppressed, e.g. during adjustment. Direct viewing into the beam with optical aids, e.g. a magnifying glass, is dangerous.

Laser equipment of the Class 2M can be employed without further protective measures, when deliberate viewing into the laser beam or into a beam reflected by mirrors is not longer than 0.25 s.

Since generally the presence of the eye-closure reflex should not be assumed, one should close the eyes or immediately turn away if the laser radiation impinges on the eye.

The following information labels are fitted to the sensor housing (front and rear side):

IEC label 29xx-25/BL, -50/BL, -100/BL

IEC label 29xx-10/BL
Chinese label 29xx-25/BL -50/BL -100BL
The laser labels for Germany are already printed on. The labels for other areas are enclosed and must be fitted by the user for the region applicable in each case before the equipment is put into operation.
Lasers of Class 2M are not subject to notification and a laser protection officer is not required. Mark the laser area recognizable and everlasting.

If both information labels are hidden in the installed state, the user must ensure that additional labels are fitted at the point of installation.

Fig. 1 True reproduction of the sensor with its actual location of the warning label, IEC label 29xx-25/BL, -50/BL, -100BL
Fig. 2 True reproduction of the sensor with its actual location of the warning label, IEC label 29xx-10
3. Functional Principle, Technical Data

3.1 Short Description

3.1.1 Measuring Principle

The scanCONTROL 29xx/BL sensor operates according to the principle of optical triangulation (light intersection method):
- A laser line is projected onto the target surface via a linear optical system.
- The diffusely reflected light from the laser line is replicated on a sensor array by a high quality optical system and evaluated in two dimensions.

The laser line triangulation corresponds in principle to the triangulation of a laser point. In addition, during the measurement a row of lines are simultaneously illuminated by the laser line. Apart from the distance information (Z-axis), the exact position of each point on the laser line (X-axis) is also acquired and output by the system.

3.1.2 System Setup

The scanCONTROL 29xx/BL sensor is a compact sensor with an integrated controller. All necessary integral parts are combined in one housing.

3.1.3 Special Performance Features

- scanCONTROL 29xx/BL features speed and compact design with simultaneously high measurement accuracy. A special line-scanning optical system ensures uniform exposure of the measuring field.
- The sensor array is arranged in the sensor head according to the Scheimpflug condition which facilitates uniform image focusing over the whole depth of the measurement range (Z-axis).
- The scanCONTROL 2910/2960 series with integrated profile analysis works even without a PC in conjunction with saved configurations. The sensor runs the profile measurement internally and calculates default measured values such as angle or edge position.

Besides measurement value output via Ethernet (Modbus TCP protocol, UDP protocol) and RS422 (Modbus RTU protocol or ASCII format), additional switching signals (results of the determination of limit values) and analog measurement values can be output. This is done by an optional scanCONTROL Output Unit, which transforms the determined measurement signals in switching and analog signals for further processing in a PLC.
3.1.4 Advantages of the Used Sensor Array (Difference to Conventional Line Scanners)
- A global shutter (high speed shutter) for the whole profile enables a high profile accuracy for fast applications without “tilting”.
- The array enables the simultaneous exposure and reading of the previous image. Thus the exposure time is longer at the same profile frequency. With it also dark objects can be measured with a high rate.

3.1.5 Further Features
- External synchronization and triggering
- Serial interface (RS422) for communication with PLC or PC
- Digital switching inputs, selectable TTL or HTL
- The automatic control of the exposure time enables consistent measurement results with changing surfaces. This function can be switched off on request.
- Ethernet 100/1000 Mbit as fast standard connection to PC
### 3.2 Technical Data

<table>
<thead>
<tr>
<th>Model</th>
<th>scanCONTROL</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>29xx-10/BL</td>
</tr>
<tr>
<td>Measuring range Z-axis</td>
<td>8 mm</td>
</tr>
<tr>
<td>Start of measuring range</td>
<td>53 mm</td>
</tr>
<tr>
<td>End of measuring range</td>
<td>61 mm</td>
</tr>
<tr>
<td>Start of measuring range, extended, approximately</td>
<td>-</td>
</tr>
<tr>
<td>End of measuring range, extended, approximately</td>
<td>-</td>
</tr>
<tr>
<td>Line length midrange (X-axis)</td>
<td>10 mm</td>
</tr>
<tr>
<td>Linearity $^1$</td>
<td>$\pm 0.17 %$ FSO (2 $\sigma$)</td>
</tr>
<tr>
<td>Reference resolution $^2$</td>
<td>1 $\mu$m</td>
</tr>
<tr>
<td>Resolution X-axis</td>
<td>1280 points/profile</td>
</tr>
<tr>
<td>Profile frequency (depends on sensor model)</td>
<td>Up to 2000 Hz</td>
</tr>
<tr>
<td>Light source laser</td>
<td>Semiconductor laser approx. 405 nm</td>
</tr>
<tr>
<td>Laser power</td>
<td>7 mW (laser class 2M), reduced 2 mW</td>
</tr>
<tr>
<td>Protection class (DIN EN 60529)</td>
<td>IP 65</td>
</tr>
<tr>
<td>Operating temperature</td>
<td>0 °C up to +45 °C (+32 ° ... +113 °F)</td>
</tr>
<tr>
<td>Storage temperature</td>
<td>-20 °C up to 70 °C (-4 ° ... +158 °F)</td>
</tr>
<tr>
<td>Outputs/inputs</td>
<td>Ethernet, Laser on/off (optional), 1 x RS422 programmable (half-duplex), 3 switching inputs programmable HTL/TTL, all inputs and outputs galvanically isolated</td>
</tr>
</tbody>
</table>
### Functional Principle, Technical Data

**Model**

<table>
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<tr>
<th>Interfaces</th>
<th>Ethernet GigE Vision</th>
<th>GigE Vision</th>
</tr>
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<td>Multifunction port</td>
<td>Digital inputs</td>
<td>GigE Vision</td>
</tr>
<tr>
<td>RS422 (half duplex)</td>
<td>Output of measurement values, sensor control, profile data transmission</td>
<td>GigE Vision</td>
</tr>
<tr>
<td>Output of measurement values</td>
<td>Ethernet (UDP) / Modbus (TCP); RS422 (ASCII / Modbus RTU)</td>
<td>GigE Vision</td>
</tr>
<tr>
<td>Display/LED</td>
<td>1 x Laser ON/OFF, 1 x Power/Error/Status</td>
<td>GigE Vision</td>
</tr>
<tr>
<td>Supply</td>
<td>11 ... 30 VDC, 500 mA</td>
<td>GigE Vision</td>
</tr>
<tr>
<td>IEEE 802.3af class 2, Power over Ethernet</td>
<td>GigE Vision</td>
<td></td>
</tr>
<tr>
<td>Dimensions</td>
<td>118.5 x 85 x 33 mm</td>
<td>GigE Vision</td>
</tr>
<tr>
<td>Weight sensor (without cable)</td>
<td>440 g</td>
<td>GigE Vision</td>
</tr>
</tbody>
</table>

FSO = Full Scale Output  |  MMR = Midrange
1) Standard measuring range
2) Measuring object: MICRO-EPSILON standard object (metallic, diffusely reflecting material)
3) According to a one-time averaging across the measuring field (640 points)
4) RS422 interface, programmable as serial interface or input for triggering / synchronisation
5) Only with Output Unit

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### scanCONTROL 29xx/BL

- **29xx-10/BL**
- **29xx-25/BL**
- **29xx-50/BL**
- **29xx-100/BL**

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### 3.3 LED Displays

<table>
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<th>LED laser on</th>
<th>Green: Laser on</th>
</tr>
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<tr>
<td><strong>LED state:</strong>&lt;br&gt;Two-color LED (red / green)</td>
<td>Green: Measurement&lt;br&gt;Green flashing: data transmission&lt;br&gt;Red flashing: error code, see Chap. 11.</td>
</tr>
</tbody>
</table>

Note: The LED state flashes green, long during active data transmission and short for controller accesses.
4. Delivery

4.1 Unpacking

- 1 Sensor scanCONTROL 29xx/BL
- 1 Assembly instructions
- 1 Sensor inspection log
- 2 Protective caps
- 1 PC2600/2900-5 Multifunction cable; 5 m long; for power supply, trigger and RS422; Escha screw connector and free cable ends
- Additionally:
  - Other scanCONTROL 29xx/BL sensors: 1 scanCONTROL demo CD with drivers, programs and documentation.

Check for completeness and shipping damage immediately after unpacking.

In case of damage or missing parts, please contact the manufacturer or supplier immediately.

You will find recommended and optional accessories in appendix, see Chap. A 1.1, see Chap. A 1.2.

4.2 Storage

Storage temperature: -20 ... +70 °C (-4 ... +158 °F)
Humidity: 5 - 95 % (non condensing)
5. Mounting and Installation

5.1 Attachment and Mounting

- using M5 screws, screwed directly
- using M4 screws, screwed pushed through

Depending on the installation position it is recommended to determine the position of the sensor for example by adjusting screws on the specially marked attachment points.

The pin hole ø3H7 is provided for a position locking pin. The sensor can be mounted reproducible and replaceable together with an attachment point, see Fig. 3, see Fig. 4, see Fig. 5, see Fig. 6.

The mounting dimensions refer to the dimensional drawings.

Pay attention to careful handling during mounting and operation.

> Damage to or destruction of the sensor

The laser beam should strike the target surface at right angles. Otherwise, inaccurate measurements cannot be excluded.

Mount the sensor by means of screws type M5 or by means of through bores for M4 according to the drawing.

<table>
<thead>
<tr>
<th>Bolt connection</th>
<th>Through length</th>
<th>Screw</th>
<th>Washer</th>
<th>Torque</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>33 mm</td>
<td>M4 x ISO 4762-A2</td>
<td>A 4.3 ISO 7089-A2</td>
<td>2 Nm ($\mu = 0.12$)</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Direct fastening</th>
<th>Screw depth</th>
<th>Screw</th>
<th>Torque</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>min 8 mm, max 10 mm</td>
<td>M5 x ISO 4762-A2</td>
<td>3.5 Nm ($\mu = 0.12$)</td>
</tr>
</tbody>
</table>

Fig. 1 Mounting conditions

The bearing surfaces surrounding the fastening holes (through-holes) are slightly raised.

Mount the sensor only to the mounting options on a flat surface. Clamps of any kind are not permitted. Do not exceed torques.

> Inaccurate, erroneous measuring values
Mounting and Installation

Recommended attachment point

Through hole
\[ \phi 4.1 +0.1 \]
Mounting thread
M5 x 10, both sides

Positioning hole
\[ \phi 3 \text{ H11} \]

Fig. 3 Dimensional drawing sensor scanCONTROL 29xx/BL-10, dimensions in mm (inches), not to scale

scanCONTROL 29xx/BL

MR = Measuring range
SMR = Start of measuring range
MMR = Midrange
EMR = End of measuring range
**Mounting and Installation**

**Fig. 4 Dimensional drawing sensor scanCONTROL 29xx/BL-25, dimensions in mm (inches), not to scale**

MR = Measuring range  
SMR = Start of measuring range  
MMR = Midrange  
EMR = End of measuring range
Mounting and Installation

Fig. 5 Dimensional drawing sensor scanCONTROL 29xx/BL-50, dimensions in mm, not to scale

MR = Measuring range
SMR = Start of measuring range
MMR = Midrange
EMR = End of measuring range

scanCONTROL 29xx/BL
Mounting and Installation

Fig. 6 Dimensional drawing sensor scanCONTROL 29xx/BL-100, dimensions in mm, not to scale

MR = Measuring range  
SMR = Start of measuring range  
MMR = Midrange  
EMR = End of measuring range

ScanCONTROL 29xx/BL
5.2 Connections

5.2.1 General

1 Ethernet socket
2 Multifunction socket (Power supply, IO)

**Fig. 7 Output sockets arrangement**

<table>
<thead>
<tr>
<th>Designation</th>
<th>Sensor connector Pin</th>
<th>Cable color PC2600/2900-x</th>
<th>Notes</th>
<th>Connection view</th>
</tr>
</thead>
<tbody>
<tr>
<td>+Ub</td>
<td>9</td>
<td>red</td>
<td>+11V - 30V DC (rated value 24 V); max. 500mA</td>
<td></td>
</tr>
<tr>
<td>GND</td>
<td>2</td>
<td>blue</td>
<td>0V</td>
<td></td>
</tr>
<tr>
<td>+Laser on/off</td>
<td>3</td>
<td>white</td>
<td>optional</td>
<td></td>
</tr>
<tr>
<td>-Laser on/off</td>
<td>1</td>
<td>brown</td>
<td></td>
<td></td>
</tr>
<tr>
<td>RS422</td>
<td>12</td>
<td>red-blue</td>
<td>RS422 input respectively output</td>
<td></td>
</tr>
<tr>
<td>/RS422</td>
<td>11</td>
<td>gray-pink</td>
<td></td>
<td></td>
</tr>
<tr>
<td>In1</td>
<td>6</td>
<td>yellow</td>
<td>Switching input In1</td>
<td></td>
</tr>
<tr>
<td>GND-In1</td>
<td>4</td>
<td>green</td>
<td>Ground connection In1</td>
<td></td>
</tr>
<tr>
<td>In2</td>
<td>5</td>
<td>pink</td>
<td>Switching input In2</td>
<td></td>
</tr>
<tr>
<td>GND-In2</td>
<td>8</td>
<td>gray</td>
<td>Ground connection In2</td>
<td></td>
</tr>
<tr>
<td>In3</td>
<td>10</td>
<td>purple</td>
<td>Switching input In3</td>
<td></td>
</tr>
<tr>
<td>GND-In3</td>
<td>7</td>
<td>black</td>
<td>Ground connection In3</td>
<td></td>
</tr>
<tr>
<td>Screen</td>
<td>Housing</td>
<td>black</td>
<td>DC-insulated from GND</td>
<td></td>
</tr>
</tbody>
</table>

**Fig. 8 Assignment of the multifunction socket on scanCONTROL 29xx/BL**

GND: Galvanically isolated from IN1, 2, 3, RS422, Laser on/off
Laser on/off: Input galvanically isolated from GND, IN1…3, RS422
IN1, IN2, IN3, RS422: Inputs galvanically isolated from GND and Laser on/off
5.2.2 Power Supply

Connect the multifunction socket only when the power supply is switched off.

* Damage to or destruction of the sensor

Connector “multifunction socket“, see Fig. 7, pin assignment, see Fig. 8.

Range: 11 V – 30 V (rated value 24 V) DC; Last maximal 500 mA

The operating voltage is protected against reverse polarity.

The cable shield is connected with the connector housing and should be connected to the protective conductor PE of the power supply.

The shielded multifunction cable PC2600/2900-x is recommended.

The operating voltage for the scanCONTROL 29xx/BL measuring device should come from a 24 V power supply, which is only used for measuring equipment and not simultaneously for drives, contactors or similar pulse interference sources. Use a power supply with galvanic isolation.
5.2.3 RS422, Synchronization

Connector multifunction socket, see Fig. 7, pin assignment, see Chap. Fig. 8.

The scanCONTROL 29xx/BL sensor has a RS422 port according to EIA standards, which can be parameterized as input or output via software.

The RS422 port can be used to synchronize multiple sensors with each other, triggering or measured value output (for example Modbus).

The internal terminating resistor (termination $R_T = 120$ Ohm, see Fig. 9) can be activated or switched off via software. The signals must be operated symmetrically according to the RS422 standard. Primarily use RS422 driver circuits or converters. Alternatively use devices with RS422 connectors, e.g. sensors or PLC’s.

The RS422 port is galvanically isolated from GND and Laser on/off, but not from GND-In1 ... 3. When used one of the GND-In1 ... 3 should connected to the GND of the remote station in order to avoid potential differences.

---

**NOTICE**

scanCONTROL 29xx/BL supports Power over Ethernet. If the sensor is connected to a network adapter/switch that is capable of POE and if you also use the power supply of the multifunction port, these two power supplies have to be galvanically isolated.
Mounting and Installation

The multifunction socket can be used with either of the following configurations:

<table>
<thead>
<tr>
<th>Configuration</th>
<th>Direction</th>
<th>Standard setting for terminating resistor $R_T$</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Half-duplex, serial communication with 115200 Baud</td>
<td>On</td>
</tr>
<tr>
<td>1</td>
<td>Half-duplex, serial communication with 57600 Baud</td>
<td>input/output</td>
</tr>
<tr>
<td>2</td>
<td>Half-duplex, serial communication with 38400 Baud</td>
<td>input/output</td>
</tr>
<tr>
<td>3</td>
<td>Half-duplex, serial communication with 19200 Baud</td>
<td>input/output</td>
</tr>
<tr>
<td>4</td>
<td>Half-duplex, serial communication with 9600 Baud</td>
<td>input/output</td>
</tr>
<tr>
<td>5</td>
<td>External trigger input</td>
<td>input</td>
</tr>
<tr>
<td>6</td>
<td>External trigger output</td>
<td>output</td>
</tr>
<tr>
<td>7</td>
<td>CMM trigger output</td>
<td>output</td>
</tr>
</tbody>
</table>

Synchronizing several sensors with each other:

- Connect the output RS422+ (Pin 12) of sensor 1 with the input RS422+ (Pin 12) of sensor 2.
- Connect the output RS422- (Pin 11) of sensor 1 with the input RS422- (Pin 11) of sensor 2.
- Also connect both the GND-In1 - pins (Pin 4) of the sensors to each other.

Software settings:

<table>
<thead>
<tr>
<th>Setting</th>
<th>Sensor 1</th>
<th>Sensor 2</th>
<th>Sensor 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>RS422 mode</td>
<td>External trigger output</td>
<td>External trigger input</td>
<td>External trigger input</td>
</tr>
<tr>
<td>No RS422 termination</td>
<td>No (terminating resistor not active)</td>
<td>Yes (terminating resistor not active)</td>
<td>No (terminating resistor active)</td>
</tr>
</tbody>
</table>

*Fig. 10 External synchronization settings*

The sensor 1 then synchronizes the sensor 2 and further sensors as master.
5.2.4 Switching Inputs

Connector multifunction socket, see Fig. 7, pin assignment, see Fig. 8.

![Diagram of switching inputs](image)

TTL or 5 V (High)
HTL or 24 V (High)

Fig. 11 Switching Inputs

The switching inputs In1 up to In3 can be used for triggering or for connecting an encoder. All switching inputs are identical. The used circuits have an internal electrical isolation. The inputs are galvanically isolated from the GND and Laser on/off.

Each switching input has its own ground connection (Gnd-In1 to 3), which has to be connected with the external ground (synchronization/trigger source or another device).
The multifunction socket can be used with either of the following configurations:

<table>
<thead>
<tr>
<th>Configuration</th>
<th>In1</th>
<th>In2</th>
<th>In3</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 Encoder with index, positive edge works with the index</td>
<td>N</td>
<td>A</td>
<td>B</td>
</tr>
<tr>
<td>1 Encoder without index, additionally external trigger possible</td>
<td>Trigger</td>
<td>A</td>
<td>B</td>
</tr>
<tr>
<td>2 External trigger</td>
<td>Trigger</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3 External trigger, load up to 4 usermodes</td>
<td>Trigger</td>
<td>Mode Bit 0</td>
<td>Mode Bit 1</td>
</tr>
<tr>
<td>4 Load up to 8 usermodes</td>
<td>Mode Bit 0</td>
<td>Mode Bit 1</td>
<td>Mode Bit 2</td>
</tr>
<tr>
<td>5 Transmit in time stamp, (only 2910/2960)</td>
<td>Bit 0</td>
<td>Bit 1</td>
<td>Bit 2</td>
</tr>
</tbody>
</table>

Signal level (switching level):

The signal levels are switchable for all switching inputs together via software between LLL (low-voltage-, TTL logic) and HLL (high-voltage-, HTL logic):

- **LLL level:**
  - Low: 0 V… 0.8 V
  - High: 2.4 V… 5 V
  - Internal pull-up: 10 kOhm to 5 V

- **HLL level:**
  - Low: 0 V… 3 V
  - High: 11 V… 24 V (permitted up to 30 V)
  - Internal pull-up: 10 kOhm to 24 V

- **Pulse duration:** ≥ 5 μs

Use a shielded cable with twisted wires, especially the recommended connection cable PC2600/2900-x from the accessories, see Chap. A 1.2.

Connect the cable shield with the potential equalization PE or the connector housing.

1) The encoder input counts each edge. Encoder output typically 4 edges per encoder step.
5.2.5 Ethernet Connection

Connector “Ethernet”, see Fig. 7.

The Ethernet connection is the standard connection to the PC.

The sensor supports the transmission with 100 Mbit and 1 Gbit.

<table>
<thead>
<tr>
<th>RJ45 connector</th>
<th>8-pin. screw connector (sensor side)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pin no.</td>
<td>Color stranded hook-up wire SC2600/2900-x</td>
</tr>
<tr>
<td>1</td>
<td>white (orange)</td>
</tr>
<tr>
<td>2</td>
<td>orange</td>
</tr>
<tr>
<td>3</td>
<td>white (green)</td>
</tr>
<tr>
<td>4</td>
<td>blue</td>
</tr>
<tr>
<td>5</td>
<td>white (blue)</td>
</tr>
<tr>
<td>6</td>
<td>green</td>
</tr>
<tr>
<td>7</td>
<td>white (brown)</td>
</tr>
<tr>
<td>8</td>
<td>brown</td>
</tr>
</tbody>
</table>

View on pin side male cable connector

View on solder pin side screw connector

Fig. 12 Pin assignment Ethernet connection
We recommend the Gigabit-Ethernet connection cable SC2600/2900-x for the Ethernet connection; cable length x in meters. Characteristics: 4 x 2 x 0.14 mm²; shielded.

Due to a high data rate, we recommend using a high-quality Ethernet PC plug-in card, for example Intel-Pro/1000 PT. The sensors are to be preferably connected directly to the network connection or by means of a high-quality switch. As a hub would result in a massive data collision it cannot be used. The PC should have one or more network cards only for the sensors.

The operation of the sensor via Ethernet does not require any driver installation. However, the network settings have to be done correctly:
- If more network cards are used, they have to belong to different networks, for example different Class-C-sub networks, however they may not belong to the same Class-B sub network.
- The sensor supports an automatically, sensor-adapted IP address in the link-local-net (169.254.x.x). No collision testing is effected.
- The sensor supports the DHCP protocol. This setting is activated by default and has priority over the retrieval in the link-local-net.
- A fixed IP address can be given.
- Various network settings can interfere the connection to the sensor (for example Firewall or packet filter).
- We recommend using a packet size of 1024 bytes/packet (payload), because network components support such packages by default. The sensor supports jumbo frames up to 4096 bytes/packet (payload), but then all the network components must also support jumbo frames of this size.

Use the program SensorFinder.exe for network configuration. You will find this program on the delivered CD.
5.2.6 External Laser Switching (Optional)

Connector multifunction socket, see Fig. 7, pin assignment, see Fig. 8.

Function
- Laser on: Voltage between +laser on/off and -laser on/off 2.8 V… 31 V, I < 5 mA
- Laser off: Voltage between +laser on/off and -laser on/off < 0.8 V or open

![Diagram showing laser switching options](image)

**Fig. 13 Options to switch off the laser**

Use a serial key switch inside the control circuit to switch off the laser.

If the voltages between pin 3 and pin 1 are < 0.8 V, the laser is off. No external resistor is necessary to the current limitation. Connect pin 1 with 2 and pin 3 with 9 for permanent “laser on“.

The external laser switching-off is implemented as a hardware solution and is a top priority. The laser can be switched off, in addition, also by software.
5.3 Installation Instructions
- Only use shielded cables from the accessories for all connection cables, see Chap. A 1.2.
- Connect the cable shields to the potential equalization on the evaluation unit (switch cabinet, PC housing, connector housing) and avoid ground loops.
- Lay all connection cables in accordance with the generally applicable measuring technology regulations, i.e. for example not directly next to pulse-carrying lines, preferably in a separate cable duct.
- The minimum bending radii of the recommended cables for flexible laying must not be less 80 mm.
- MICRO-EPSILON recommends the use of the optionally available power supply PS2020, DIN rail mounting, input 230 VAC, output 24 VDC/2.5 A, see Chap. A 1.1.

5.4 Getting Ready for Operation, Commissioning
- Mount the sensor according to the installation instructions, see Chap. 5.1.
- Connect the sensor to the Ethernet cable.
- Connect the sensor to downstream display or monitoring units and to the power supply.
- Switch on the power supply.
6. Operation of the Sensor with a PC

6.1 Displays

After getting ready for operation, switch on the external direct current power supply (24 VDC).

The state LED indicates different error conditions by flashing, see Chap. 11. If several errors occur at the same time, it indicates two of them alternately. Therefore the LED can continue to flash for some time after the rectification of an error. If no flashing occurs for several seconds, no error has occurred.

The scanCONTROL 29xx/BL sensor needs a running-in time of typically 20 minutes for high precision measurements.

6.2 Operating and Demonstration Programs

A CD-ROM is provided for the operation of the sensor: As well as the installation instructions mentioned above, the CD-ROM also contains various documentation and programs:

- The demonstration program DeveloperDemo.exe in the directory [CD]:\Program\Developer Demo is used for scanner parameterization and simple display of profile data.
- The directory [CD]:\Development\SDK contains a sensor-specific DLL and descriptions and examples for creating your own user programs with the C++ programming language. It can also be used with C, Delphi or other programming languages. The associated descriptions for the DLL in German and in English can be found in the same directory.
- scanCONTROL Configuration Tools is used to analyze typical measurement tasks for scanCONTROL 29xx/BL.
- scanCONTROL 3D-View visualizes three dimensional point data, which are recorded with scanCONTROL 29xx/BL.

The measuring fields are partially used in the demonstration programs, see Chap. 6.4.1.
6.3 Installation

6.3.1 Requirements
The following minimum system specification is necessary for the operation of the scanCONTROL software packages:
- Windows XP SP2 (32 bit), Windows Vista (32 bit), Windows 7 (32 bit and 64 bit), Windows 10 (32 bit and 64 bit)
- Pentium III ≥ 800 MHz
- 512 MB RAM
- Screen resolution: 1024x768

To be able to use the software the following steps must be followed:
1. Install the Ethernet interface hardware, if not already installed.
2. Install the software according to the instructions on the CD.
3. Connect and license the USB dongle, if present.
4. Connect the scanCONTROL 29xx/BL measuring system to the PC via Ethernet.

6.3.2 Connecting scanCONTROL 29xx/BL to the PC
Proceed as follows in order to connect scanCONTROL 29xx/BL via Ethernet with the PC.

- Finish the installation of the software completely.
- Connect scanCONTROL 29xx/BL via the Ethernet interface to the PC and switch on the power supply.
- Please wait until the scanCONTROL 29xx/BL device is recognized by the PC.

This may take a few seconds.
The system is now ready to operate the scanCONTROL 29xx/BL measurement system with the scanCONTROL software packages.
6.4 Instructions for Operation

6.4.1 Measuring Field Selection

The optical design of the sensor satisfies the so-called “Scheimpflug condition” which ensures optimum mapping over the complete measuring range. In doing so, the measuring range is mapped on a rectangular matrix. The distortions resulting from this are shown, see Fig. 14. The usable measuring range is always trapezoidal.

The assigned maximum x-values for the z-coordinates can be found, see Fig. 4, see Fig. 5.

Please refer to the sensor acceptance report of your sensor. A slight range shifting of a measuring field is possible and depends on the sensor.

The top edge corresponds to the start of the measuring range and the bottom edge to the end of the measuring range. The corners of the predefined measuring fields are on a grid with grid spacing of 1/8 of the matrix. The sensor matrix used in the scanCONTROL 29xx/BL supports the reading of a restricted measuring field. The following picture, see Fig. 14, shows the predefined view areas and the associated measuring fields.
Operation of the Sensor with a PC

Fig. 14 Predefined measuring fields
The measuring field can be restricted by omitting complete matrix areas in order to suppress interfering image ranges.

The following measuring fields are used in the demonstration program, see Chap. 6.2.

<table>
<thead>
<tr>
<th>Name</th>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>Large</td>
<td>0</td>
</tr>
<tr>
<td>Standard</td>
<td>2</td>
</tr>
<tr>
<td>Small</td>
<td>7</td>
</tr>
</tbody>
</table>

*Fig. 15 Measuring fields used*

Measuring field and measuring range must be clearly differentiated in practical use. The measuring field is related to the matrix and the measuring range is related to the measuring object (the object space).

Both do not have to match on account of the optical mapping and the definitions.

- The measuring field “standard“ is larger than the measuring range “standard“. The minimum dimensions can be found in the dimensional drawing, see Fig. 4, see Fig. 5.

The scanCONTROL 29xx/BL sensors are distinguished by

- a laser line with 20 ° opening angle (measuring range 25 mm) respectively 25 ° opening angle (measuring ranges 50 mm and 100 mm).
- The receiver has a smaller opening angle (view angle) than the laser line.
- Centered measuring field (symmetrical to the center axis).
- The high resolution sensor image matrix has 1280 x 1024 pixels. The measuring field geometry is fixed.
- Reference for the distance (Z-axis) is the lowest body edge of the sensor, see Fig. 4, see Fig. 5.
- Use of the GigE-Vision standard. Further informations for this can be found in the "OpManPartB.html" file on the CD-ROM.
- Standard GigE Vision implementation from different manufacturers can be used.
6.4.2 Calibration

The calibration of the sensor is performed using the complete matrix and is independent from the selected measuring field.

The trapeze form of the measuring field is produced from the projection onto the sensor matrix. The standard measuring range is framed in the center.

A sensor acceptance report is enclosed for each sensor. Three diagrams for the linearity measurement which are briefly explained in the report are included in the sensor acceptance report. The key diagram in the sensor acceptance report is shown again below, see Fig. 16.

![Fig. 16 Linearity deviation, example of an scanCONTROL 29xx/BL-50](image)

The black points show the places where the measurement error exceeds the linearity limit of 0.08 mm (depending on sensor model). The measurement error increases at both ends of the depth range and particularly in the remote corners. These areas should therefore be avoided for the measurement.
6.4.3 Automatic Exposure Time Regulation

The automatic exposure time regulation facilitates the recording of the profile with optimum exposure time (shutter time).

The “shutter time” preset by the user is used as the starting value for the automatic exposure time regulation. It should be selected so large that still valid measured values can be output at the darkest place of the profile. One of the supplied demonstration programs can be used for determining this. The automatic exposure time regulation can also be deactivated if required.

If there is no object in the measuring range, the “shutter time” stored in the shutter register of the sensor will be used as exposure time. This value must also guarantee reliable recognition of the darkest measurement object.

A previous test is recommended if the target is very dark or has very high contrast. The various demonstration programs are suitable for adjusting and testing the exposure time. In doing so, it is by all means sensible to work with several different exposure times and to observe the effect in the diagrams.

The current exposure time can be calculated from the timestamps of the measured values. It is displayed as Shutter time, see Fig. 17.
Shutter time preset by the user: 0.10 ms
Automatic shutter time is active.

Result: The sensor operates with a Shutter time of 0.05 ms.

Fig. 17 Screenshot of the developer demonstration program with automatic shutter
6.5  Error Influences

6.5.1  Reflection of the Target Surface
The sensor basically evaluates the diffuse portion of the laser line reflections. Any statement about a minimum reflection factor is only possible with reservations.

A preliminary examination is necessary for using the sensor on transparent or reflecting objects.

The method of direct reflection on reflecting surfaces as it is successfully applied for the point triangulation cannot be used for the line triangulation on account of the fan-shaped form of the laser line (central projection). Here, the receiving lens would only be able to reach a narrow area near the center. As usually curved surfaces should also be measured for the profile measurement, this range will be further narrowed.

6.5.2  Color Differences
Color differences of measurement objects have effects. However, these color differences are often also combined with different penetration depths of the laser light into the material. Different penetration depths in turn result in apparent changes of the line thickness. Therefore, color changes, combined with penetration depth changes, can result in inaccurate measurements.

As the exposure parameters can only be changed as a whole for one profile, careful matching of the exposure to the target surface is recommended.

6.5.3  Temperature Influences
A running-in time of at least 20 minutes during start-up is required in order to achieve a uniform temperature spread in the sensor.

If measurements with accuracy in the μm range are made, the effect of temperature fluctuations on the mounting must also be observed by the user.

Due to the damping effect of the thermal capacity of the sensor, fast temperature changes are only measured after a delay.
6.5.4 External Light
An interference filter in the sensor is present for suppression of external light.
In general, the shielding of external light directly emitted on the target or reflected in the sensor must be ensured using protective covers or similar.
Pay particular attention to unwanted reflections of the laser line outside the measuring object range (background, object holder or similar) which can be reflected back again into the view area of the receiver.
Matt black surface coatings are recommended for all objects outside the measuring range (object holders, transport apparatus, grippers or similar).

6.5.5 Mechanical Vibrations
If high resolutions in the μm range should be achieved with the sensor, particular attention must be paid to stable or vibration-damped sensor and measuring object mounting.

6.5.6 Surface Roughness
Surface roughness of 5 μm and more results in "surface noises" due to interference of the laser light.
Direct reflections of the laser light to the receiver can also occur at the finest grooves (e.g. abrasion marks on the surface) particularly if these run in the line direction. This can result in inaccurate measured values.
Prevention of this effect might be possible by adjusting several sensor settings e.g. exposure time, filter.

6.5.7 Shadowing Effects
- Receiver: The laser line can disappear completely or partially behind steep edges. The receiver then does not "see" these areas.
- Laser line: The fan-shaped form of the laser line inevitably results in partial shadowing at vertical edges. In order to make these areas visible, only changing the sensor or object position helps.
As a general rule, measuring objects with steep edges cannot be one hundred percent measured using laser triangulation. The missing areas can only be supplemented or interpolated using suitable software.
Shadowing of the receiver

Fig. 18 Shadowings

Shadowing of the laser line
6.6 Cleaning

6.6.1 Housing
The cleaning of the housing is not recommended. If a cleaning is to be accomplished nevertheless, this is possible with water without additives and a soft cloth.

6.6.2 Protective Housings
A periodically cleaning of the protective housings is recommended.

Dry cleaning
This requires a suitable optical antistatic brush or blow off the panels with dehumidified, clean and oil free compressed air.

Wet cleaning
Use a clean, soft, lint-free cloth or lens cleaning paper and pure alcohol (isopropanol) for cleaning the protective housing.

Do not use commercial glass cleaner or other cleansing agents.
7. **scanCONTROL Output Unit**

The measurement system scanCONTROL 2910/2960 measures and evaluates 2D profile data of a surface and supplies analog and digital control signals. scanCONTROL Output Unit

- outputs digital and analog signals,
- is based on the WAGO®-I/O-System 750,
- uses Ethernet.

Setup and operation of scanCONTROL Output Unit are exemplarily described below.

### 7.1 scanCONTROL Output Unit - Components

- Output Unit Basic, consisting of:
  - Ethernet Fieldbus Coupler with system supply unit (OU-Fieldbus Coupler/Ethernet)
  - 24V DC power supply filter (OU-Filter module) and termination module (OU-Bus termination module)
- Digital output terminal
- Analog output terminal

**Fig. 19 Example configuration Ethernet with analog and digital output module**
Mount the components of a scanCONTROL Output Unit on a top hat rail (TS35) in the described order. Without using a top hat rail a robust installation cannot be guaranteed. Ensure that each module is locked securely on the top hat rail.

Terminate the bus with the bus termination, see Fig. 19.

Each module of scanCONTROL Output Unit is described, see Chap. 7.4. Further informations can be found in the data sheet and manual of the respective module in the supplied scanCONTROL Demo-CD.

7.2 Connect the Power Supply

Digital output modules need a field supply of 5 VDC or 24 VDC depending on the module type.

Fig. 20 Separated power units for system and field supply (Ethernet)
After mounting of the modules, the required wiring has to be installed.

- Connect the “System supply (out)” terminals of the OU-Filter module to the “System supply (in)” terminals of the OU-Fieldbus Coupler (0 V and 24 V, see Fig. 20).
- Connect the system supply (in) of the OU-Filter module to the power supply (0 V and 24 V, see Fig. 20).
- Connect the field supply (in) of the OU-Filter module to the power supply (0 V and 5 V/24 V, see Fig. 20).

The system supply and field supply should be separated to ensure the bus operation and electrical isolation in case of a short-circuit of an actor.

### 7.3 Commissioning scanCONTROL Output Unit

After having installed the required wiring of the modules of scanCONTROL Output Unit, you have to parameterize the measurement system according to your measurement task to get the desired signals at the digital and analog output ports.

- Connect the sensor to the PC using the Ethernet cable.
- Alternatively scanCONTROL Output Unit can be connected simultaneously to the PC and to the sensor.

Parameterize the measurement system using scanCONTROL Configuration Tools and assign the desired signals to the digital and analog output ports.

When the parameterization is finished, save the settings to a user mode of the sensor.

**scanCONTROL Configuration Tools** > **Menu** > **Parameters** > **Save parameters to scanCONTROL...**

Refer to scanCONTROL Configuration Tools, Chapter 3.14.4.

- Exit scanCONTROL Configuration Tools and disconnect scanCONTROL 2910/2960, PC and if necessary scanCONTROL Output Unit.

- Connect the scanCONTROL 2910/2960 sensor to the Output Unit by using the Ethernet cable.

scanCONTROL 2910/2960 and the output unit operate now as an independent measurement system and the digital and analog signals are output via the assigned ports.
7.4 Specification of the Components

7.4.1 Output Unit Basic

Micro-Epsilon order no. 6414073

Consists of
- OU-Fieldbus Coupler/Ethernet
- OU-Filter module
- OU-Bus termination module
- Interfaces: 2x Ethernet to connect scanCONTROL 2910/2960 sensors.
- Indicators (Status LED’s, for detailed description refer to the manual of the OU-Fieldbus Coupler/Ethernet)
- The system supply is already mounted to the Fieldbus Coupler.

Fig. 21 OU-Fieldbus Coupler/Ethernet with system supply module
### System data

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max. number of bus sharing unit</td>
<td>Limited by Ethernet specification</td>
</tr>
<tr>
<td>Max. length of fieldbus segment</td>
<td>100 m</td>
</tr>
<tr>
<td>Baud rate</td>
<td>10/100 Mbit/s</td>
</tr>
</tbody>
</table>

### Technical Data

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of bus terminals</td>
<td>64</td>
</tr>
<tr>
<td>With bus extension</td>
<td>250</td>
</tr>
<tr>
<td>Power supply</td>
<td>DC 24 V (-25 % ... +30 %)</td>
</tr>
<tr>
<td>Max. input current</td>
<td>280 mA at 24 V</td>
</tr>
<tr>
<td>Internal current consumption</td>
<td>450 mA at 5 V</td>
</tr>
<tr>
<td>Total current for I/O modules</td>
<td>700 mA at 5 V</td>
</tr>
<tr>
<td>Voltage drop at $I_{\text{max}}$</td>
<td>$&lt; 1$ V at 64 I/O modules</td>
</tr>
</tbody>
</table>

*Fig. 22 Technical data Fieldbus Coupler/Ethernet*

#### 7.4.2 Supported Modules

- 8-Channel digital output module; DC 24 V; 0.5 A; high-side switching; 8 actors; short-circuit prooved;
  Micro-Epsilon order no. 0325115, see Chap. 7.4.3; power supply through power jumper contacts
- 8-Channel digital output module; DC 24 V; 0.5 A; low-side switching; 8 actors; short circuit prooved;
  Micro-Epsilon order no. 0325131; power supply through power jumper contacts
- 4-Channel analog output module; 0 - 10 V; Micro-Epsilon order no. 0325135, see Chap. 7.4.4
- 4-Channel analog output module; ±10 V; Micro-Epsilon order no. 0325116
- 4-Channel analog output module; 0 – 20 mA; Micro-Epsilon order no. 0325132
- 4-Channel analog output module; 4 – 20 mA; Micro-Epsilon order no. 0325133
7.4.3 OU-DigitalOut/8-Channel/DC24 V/0.5 A/High-side Switching/8 Actuators

- Micro-Epsilon order no. 0325115
- The 8-Channel digital output module DC 24V 0.5 A is short-circuit-proofed, high-side switching, for TS35, CAGE CLAMP® connections, 8 actuators.
- The field level is galvanically isolated to the system level.
- The indicators (Status LED’s) additionally show the status of the digital outputs (IO/NIO), for detailed description refer to manual of the 8-Channel digital output modules DC 24 V 0.5A, 8 actuators, high-side switching
- Actuators can be operated at all digital outputs and be wired directly via DO 1/2/3/4/5/6/7/8.
- scanCONTROL 2910/2960 supports eight digital outputs.

Fig. 23 8-Channel DigitalOut-Module

<table>
<thead>
<tr>
<th>Number of outputs</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current consumption (internal)</td>
<td>25 mA</td>
</tr>
<tr>
<td>Voltage via power jumper contacts</td>
<td>DC 24 V (-25 % / +30 %)</td>
</tr>
<tr>
<td>Type of load</td>
<td>resistive, inductive, lamps</td>
</tr>
<tr>
<td>Switching rate ( \text{max.} )</td>
<td>2 kHZ</td>
</tr>
<tr>
<td>Output current</td>
<td>0.5 A short-circuit-proofed</td>
</tr>
<tr>
<td>Energy dissipation ( W_{\text{max.}} ) (unique switching off)</td>
<td>0.9 J</td>
</tr>
<tr>
<td>( L_{\text{max.}} = 2 W_{\text{max.}}/I^2 )</td>
<td></td>
</tr>
<tr>
<td>Current consumption typ. (field side)</td>
<td>15 mA (per module) + load</td>
</tr>
</tbody>
</table>

Fig. 24 Technical data of the digital output module
7.4.4 OU-AnalogOut/4-Channel/0-10 V

- Micro-Epsilon order no. 0325135
- 4-Channel analog output module DC 0-10 V
- Indicators (Status-LED’s, for detailed description refer to manual of the 4-Channel analog output module DC 0-10 V)
- Voltage range is terminal-related 0 to +10 V and can not be extended by changing the appropriate setting in scanCONTROL Configuration Tools.
- The output signal is galvanically isolated output from the system level.
- The resolution is limited to 12 bits.
- scanCONTROL 2910/2960 supports four analog outputs.

**Fig. 25 4-Channel-AnalogOut-Modul**

<table>
<thead>
<tr>
<th>Number of outputs</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power supply</td>
<td>via system voltage DC/DC</td>
</tr>
<tr>
<td>Signal voltage</td>
<td>0 V ... 10 V</td>
</tr>
<tr>
<td>Load</td>
<td>&gt; 5 kΩ</td>
</tr>
<tr>
<td>Resolution</td>
<td>12 bit</td>
</tr>
<tr>
<td>Conversion time</td>
<td>typ. 10 ms</td>
</tr>
<tr>
<td>Setting time</td>
<td>typ. 100 μs</td>
</tr>
<tr>
<td>Measurement error at 25 °C</td>
<td>&lt; ± 0.1 % of full scale (FS)</td>
</tr>
<tr>
<td>Temperature coefficient</td>
<td>&lt; ± 0.01 % /K of full scale (FS)</td>
</tr>
</tbody>
</table>

**Fig. 26 Technical data of analog output module**
8. Warranty

All components of the device have been checked and tested for perfect function in the factory. In the unlikely event that errors should occur despite our thorough quality control, this should be reported immediately to MICRO-EPSILON. The warranty period lasts 12 months following the day of shipment. Defective parts, except wear parts, will be repaired or replaced free of charge within this period if you return the device free of cost to MICRO-EPSILON.

This warranty does not apply to damage resulting from abuse of the equipment and devices, from forceful handling or installation of the devices or from repair or modifications performed by third parties. No other claims, except as warranted, are accepted. The terms of the purchasing contract apply in full.

MICRO-EPSILON will specifically not be responsible for eventual consequential damages.

MICRO-EPSILON always strives to supply the customers with the finest and most advanced equipment. Development and refinement is therefore performed continuously and the right to design changes without prior notice is accordingly reserved.

For translations in other languages, the data and statements in the German language operation manual are to be taken as authoritative.

9. Service, Repair

In a case of a defect on scanCONTROL 29xx/BL:
- If possible, save the current sensor settings in a parameter set, see Configuration Tools, menu Parameters > Save parameters to file..., in order to load the settings back again into the sensor after the repair.
- Please send us the effected parts for repair or exchange.

In the case of faults the cause of which is not clearly identifiable, the whole measuring system must be sent back to:

MICRO-EPSILON Optronic GmbH
Lessingstraße 14
01465 Dresden - Langebrück / Germany
Tel. +49 (0) 35201 / 729-0
Fax +49 (0) 35201 / 729-90
optronic@micro-epsilon.de
www.micro-epsilon.com
10. Decommissioning, Disposal

Disconnect all cables between the scanCONTROL 29xx/BL sensor and the following control or evaluation units.

Incorrect disposal may cause harm to the environment.

Dispose of the device, its components and accessories, as well as the packaging materials in compliance with the applicable country-specific waste treatment and disposal regulations of the region of use.
## 11. Error Codes

(— LED state lights for a long time lang, • LED state lights briefly)

<table>
<thead>
<tr>
<th>Flashing sequence</th>
<th>Cause</th>
<th>Remedy</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Group: Loading / saving configuration</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>.. 2x short</td>
<td>Mode not found.</td>
<td>Select different one.</td>
<td>Only previously stored modes can be called up.</td>
</tr>
<tr>
<td>..- 2x short, 1x long</td>
<td>White error flash</td>
<td>Contact manufacturer, return sensor.</td>
<td>Should not occur in normal operation.</td>
</tr>
<tr>
<td>… 3x short</td>
<td>Flash full</td>
<td>None, contact manufacturer.</td>
<td>Should not occur in normal operation.</td>
</tr>
<tr>
<td>…. 4x short</td>
<td>Loading suppressed due to active data transmission.</td>
<td>Stop active data transmission.</td>
<td>Prevents PC software crashes.</td>
</tr>
<tr>
<td>Group: Data processing and transmission</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>-- 2x long</td>
<td>Data overflow in the sensor</td>
<td>Select smaller measuring field, reduce profile frequency, select less complex measuring program.</td>
<td>Data can be impaired; exposure time can be longer than expected.</td>
</tr>
<tr>
<td>-- 2x long, 1x short</td>
<td>Data overflow during receipt of the data from the sensor.</td>
<td>Select smaller measuring field, reduce profile frequency, select less complex measuring program.</td>
<td>Data can be impaired.</td>
</tr>
<tr>
<td>--.. 2x long, 2x short</td>
<td>Data overflow for serial port RS422</td>
<td>Reduce profile frequency, select less complex measuring program.</td>
<td>Data can be impaired.</td>
</tr>
</tbody>
</table>
## Error Codes

<table>
<thead>
<tr>
<th>Flashing sequence</th>
<th>Cause</th>
<th>Remedy</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>--..</td>
<td>2x long, 3x short</td>
<td>Data overflow during transmission of the data via Ethernet</td>
<td>Reduce profile frequency, increase packet size.</td>
</tr>
<tr>
<td>--.....</td>
<td>2x long, 5x short</td>
<td>Error during calculation</td>
<td>Reduce profile frequency, select faster calculation mode.</td>
</tr>
<tr>
<td>--......</td>
<td>2x long, 6x short</td>
<td>Error during Ethernet transmission</td>
<td>Reduce profile frequency.</td>
</tr>
</tbody>
</table>

**Group: Ethernet interface**

<table>
<thead>
<tr>
<th></th>
<th>Cause</th>
<th>Remedy</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
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</tbody>
</table>

The state LED flashes green; long during active data transmission and short for controller accesses. A controller access can cause various data overflows particularly if the measuring frequency is near its maximum.
### Appendix

#### A 1 Accessories

##### A 1.1 Recommended Accessories

<table>
<thead>
<tr>
<th>Description</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>PS2020</td>
<td>Power supply for DIN rail mounting, input 230 VAC, output 24 VDC/2.5 A for maximum 2 sensors scanCONTROL 29xx/BL at the same time.</td>
</tr>
</tbody>
</table>

##### A 1.2 Optional Accessories

<table>
<thead>
<tr>
<th>Description</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>PC2600/2900-x</td>
<td>Multifunction cable, (length x = 10, 20 m), cable 6x2x0.14 shielded, with integrally cast 12-pole M12x1 screw connector and free cable ends</td>
</tr>
</tbody>
</table>

---

**scanCONTROL 29xx/BL**

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SC2600/2900-x

Ethernet connection cable (length x = 0.5, 2, 5, 10, 15, 20, 25, 28, 35 m) cable 4x2x0.14; shielded, with integrally cast 8-pole M12x1 screw connector and 8-pole Ethernet cable connector RJ45.

The cable are cable carriers suitable.