Measuring Range and Output Characteristics

For each sensor a minimum distance to the target (measurement object) must be maintained. This avoids a measurement uncertainty due to the sensor pressing on the target and mechanical damage to the sensor/target. Start of measuring range (SMR) of DT3005-U1-x-C1 is 0.1 mm.

Displacement signal

5 V  0.5 V

0 %  100 %

SMR

Measuring range

Sensor

Target

Fig. 1 Start of measuring range (SMR), the smallest distance between sensor face and measuring object

Decommissioning, Disposal

Disconnect the power supply and output cable on the sensor. Incorrect disposal may cause harm to the environment. Dispose of the device, its components and accessories, as well as the packaging materials in compliance with the applicable country-specific waste treatment and disposal regulations of the region of use.

Liability for Material Defect

All components of the device have been checked and tested for functionality at the factory. However, if defects occur despite our careful quality control, MICRO-EPSILON or your dealer must be notified immediately.

The liability for material defects is 12 months from delivery. Within this period, defective parts, except for wearing parts, will be repaired or replaced free of charge, if the device is returned to MICRO-EPSILON with shipping costs prepaid. Any damage that is caused by improper handling, the use of force or by repairs or modifications by third parties is not covered by the liability for material defects. Repairs are carried out exclusively by MICRO-EPSILON.

Additional claims cannot be made. Claims arising from the purchase contract remain unaffected. In particular, MICRO-EPSILON shall not be liable for any consequential, special, indirect or incidental damage.

In the interest of further development, MICRO-EPSILON reserves the right to make design changes without notification.

For translations into other languages, the German version shall prevail.

Installation Conditions

The relative size of the measuring object to the sensor has effects on the linearity deviation for eddy current sensors. Ideally, the measuring object size is at least 4 times the sensor diameter.

Fig. 2 Assembly, dimensions in mm (not to scale)

Fig. 3 Measurement uncertainty depending on distance A and target material

Optional Accessories

PCx/5 Power supply and output cable, x m long

Clamping

Flange

12 mm

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X9771337.01-A03188HDR
Safety
System operation assumes knowledge of the assembly instructions. The following symbols are used in these assembly instructions:

**CAUTION**
Indicates a hazardous situation which, if not avoided, may result in minor or moderate injury.

**NOTICE**
Indicates a situation that may result in property damage if not avoided.

**i**
Indicates a tip for users.

**Warnings**
Connect the power supply and the display/output device according to the safety regulations for electrical equipment.

> **Risk of injury by electric shock**
> **Damage to or destruction of the sensor**

The supply voltage may not exceed the specified limits.

> **Damage to or destruction of the sensor**

Avoid shocks and impacts to the sensor.

> **Damage to or destruction of the sensor**

Protect the cable against damage.

> **Failure of the measuring device**

**Intended Use**
The eddyNCDT 3005 is designed for use in industrial and laboratory applications. It is used for displacement, distance, thickness and movement measurement and for position measuring of parts or machine components. The system must only be operated within the limits specified in the technical data. The system must be used in such a way that no persons are endangered or machines and other material goods are damaged in the event of malfunction or total failure of the system. Take additional precautions for safety and damage prevention in case of safety-related applications.

**Technical Data**

<table>
<thead>
<tr>
<th>Sensor</th>
<th>DT3005-U1-x-C1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measuring range</td>
<td>1 mm</td>
</tr>
<tr>
<td>Start of measuring range (SMR)</td>
<td>0.1 mm</td>
</tr>
<tr>
<td>End of measuring range (EMR)</td>
<td>1.1 mm</td>
</tr>
<tr>
<td>Output</td>
<td>0.5 ... 9.5 V</td>
</tr>
<tr>
<td>Power supply</td>
<td>12 ... 32 V, appr. 0.6 W</td>
</tr>
<tr>
<td>Warm-up time</td>
<td>5 minutes</td>
</tr>
<tr>
<td>Protection class</td>
<td>IP 67 (connected)</td>
</tr>
<tr>
<td>Pressure resistance sensor</td>
<td>10 bar</td>
</tr>
</tbody>
</table>

**Operating temperature**

Sensor and cable

-30 ... 125 °C

Controller

-20 ... 70 °C

**Storage temperature**

Sensor cable outer diameter

3.6 mm ± 0.2 mm

Visible sensor cable length

1 m

Min. bending radius sensor cable

20 mm, static

40 mm, dynamic

**Pin Assignment**

<table>
<thead>
<tr>
<th>Pin</th>
<th>Description</th>
<th>Color</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>+ 24 V supply</td>
<td>brown</td>
</tr>
<tr>
<td>2</td>
<td>Displacement signal</td>
<td>white</td>
</tr>
<tr>
<td>3</td>
<td>GND</td>
<td>blue</td>
</tr>
<tr>
<td>4</td>
<td>Assigned internally</td>
<td>black, gray</td>
</tr>
</tbody>
</table>

**Installation and Assembly**

No sharp or heavy objects should be allowed to affect the cable sheath or the sensor cable, the supply cable and the output cable.

> **Check all plug-in connections for firm seating before starting operation**

Construction: The front part of the sensor with encapsulated coil consists of electrically non-conducting materials.

In the radial direction metal parts in the vicinity may behave similar to the measuring object, rendering the measurement result inaccurate. Please note this by selection of material for sensor mounting and their setup.

**Measurement Setup**

Sensors of the eddyNCDT 3005 series cannot be synchronized. Observe a few simple mounting conditions for two nearby mounted sensors.

**Fig. 5 ES-U1-C-CAx, dimensions in mm (not to scale)**

**Fig. 6 DT3005-x, dimensions in mm (not to scale)**